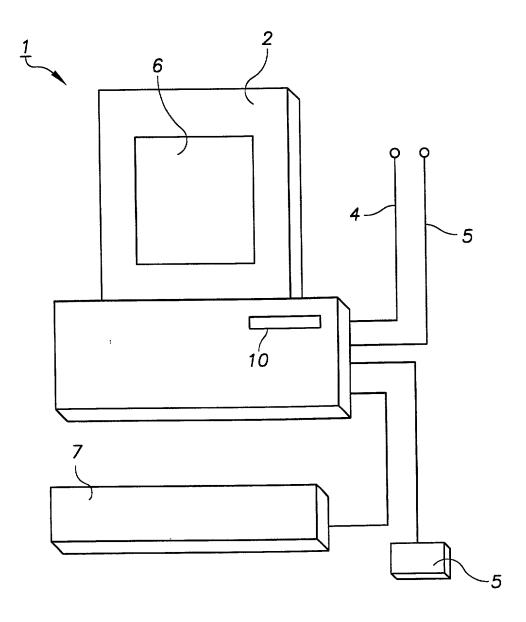
FIG. 1



HAND THE THE THE THE THE STATE OF THE STATE

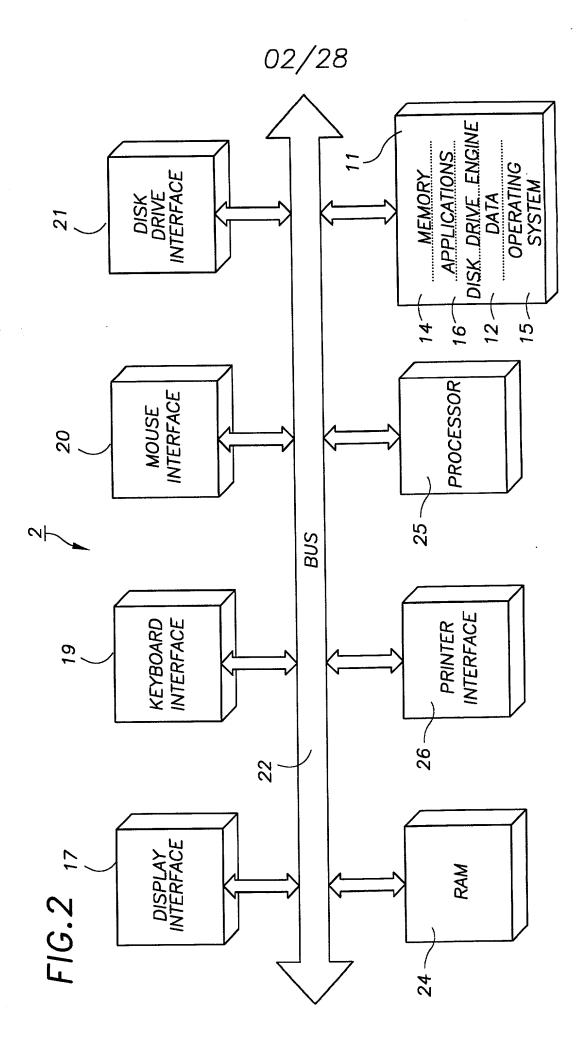
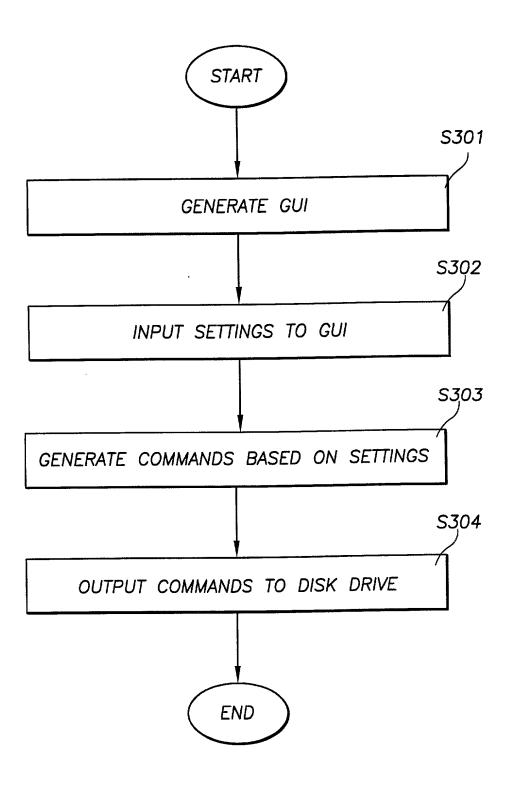
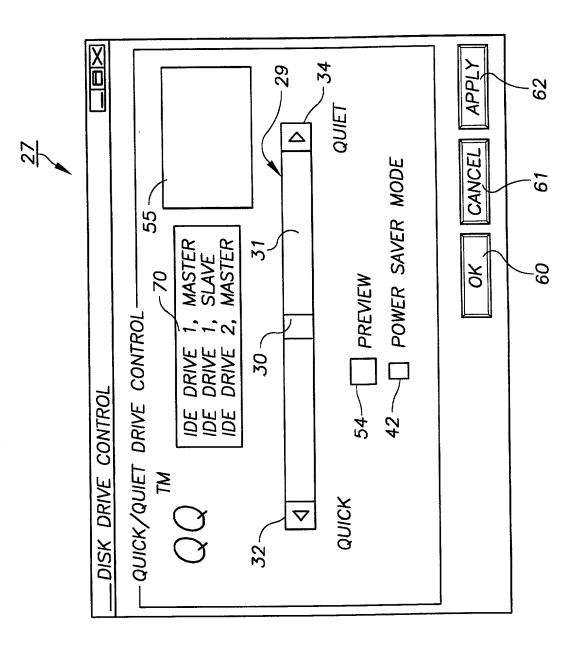


FIG.3

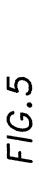


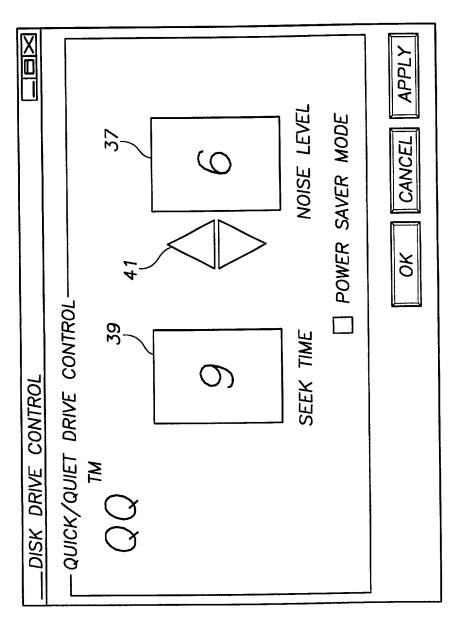


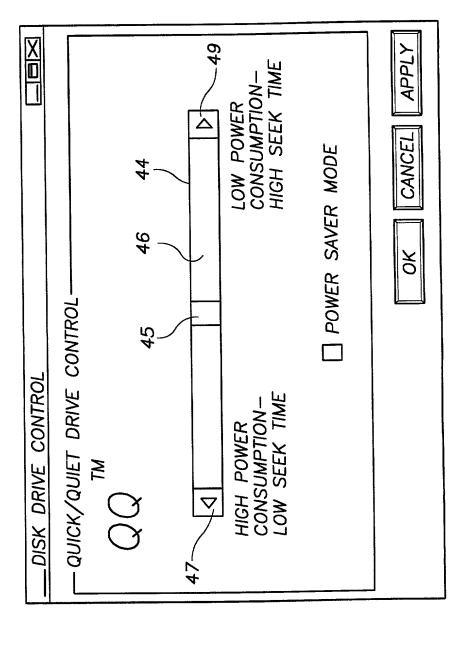
F1G.4

Water and the second

The State of Williams Control







F1G.6

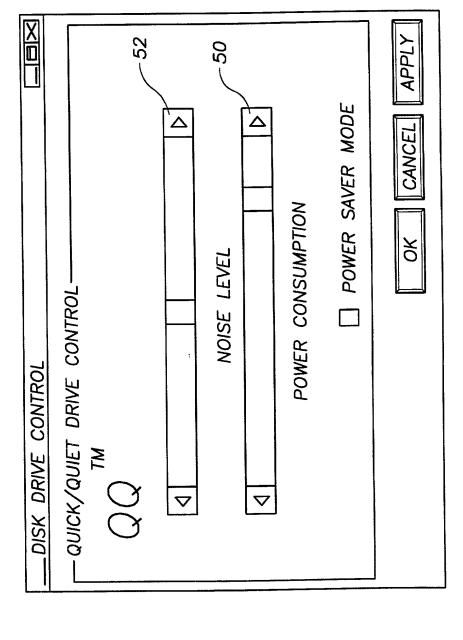
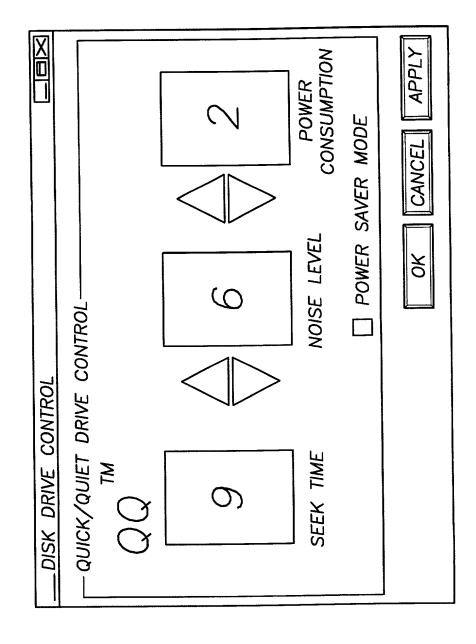


FIG.7



F1G.8

A SECTION OF THE PROPERTY OF T

IDE DRIVE 1, MASTER

IDE DRIVE 1, SLAVE

IDE DRIVE 2, MASTER

F1G.9

0 0 FIG. 10A

10/28

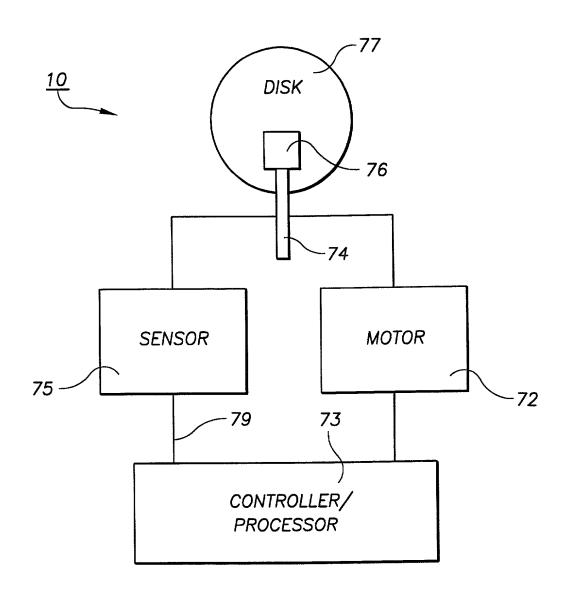
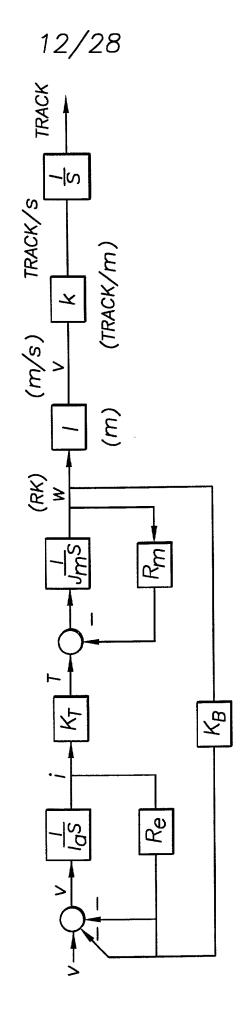


FIG. 11





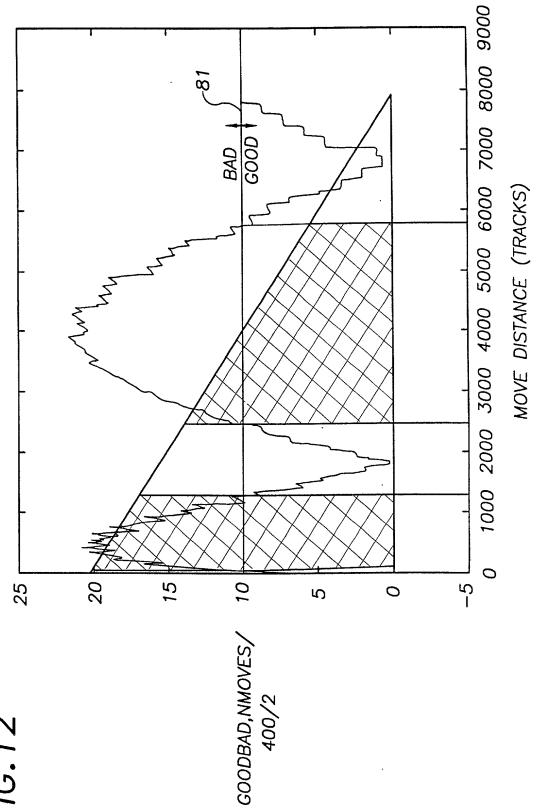


FIG. 13
PRIOR ART

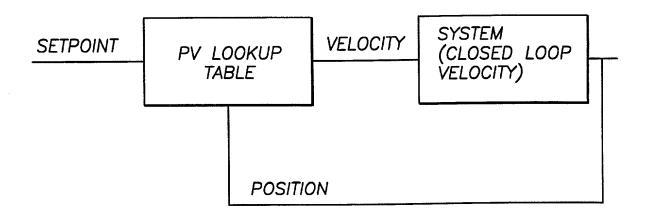


FIG. 14

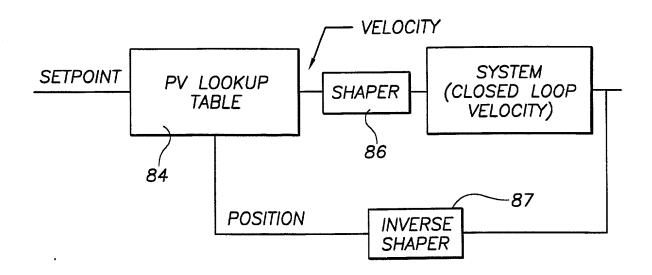


FIG. 15

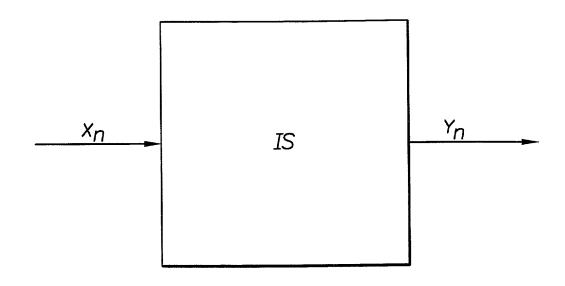


FIG. 16

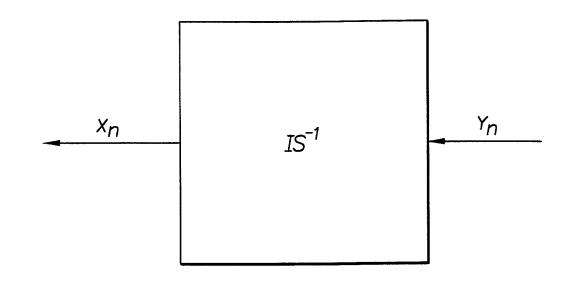


FIG. 17

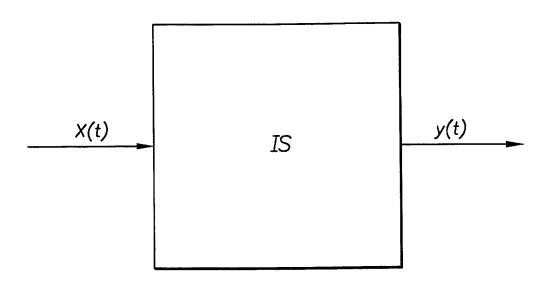
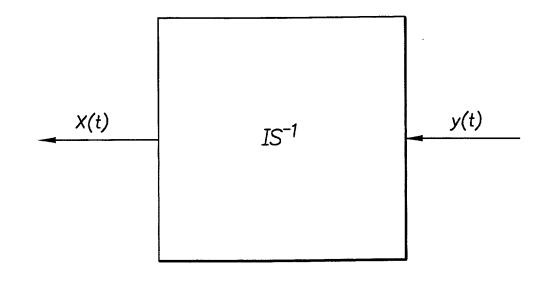


FIG18



The first first first first first in the first f

FIG.19

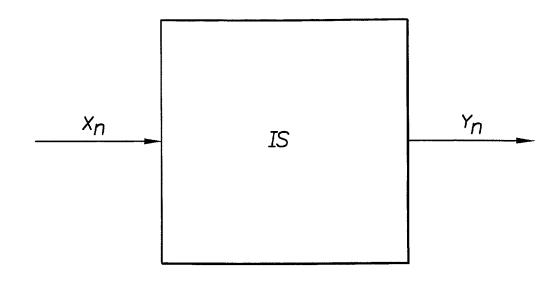
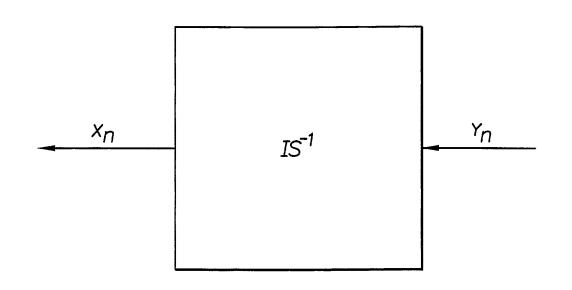
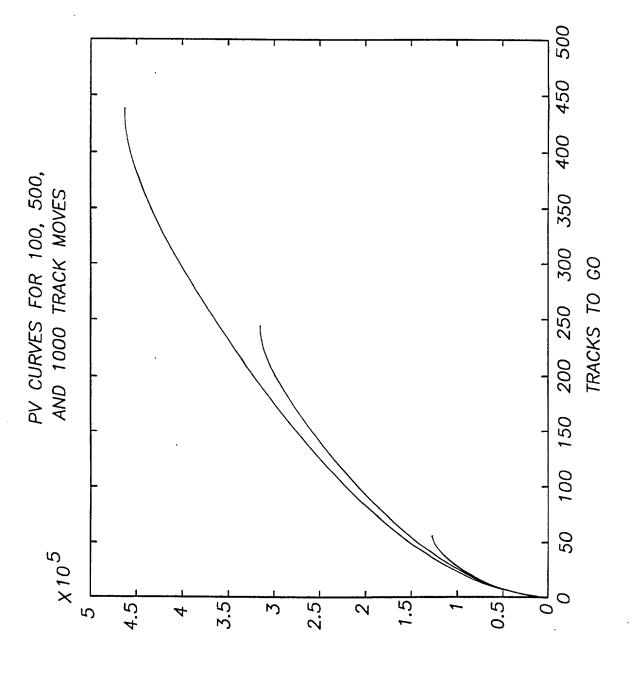


FIG20

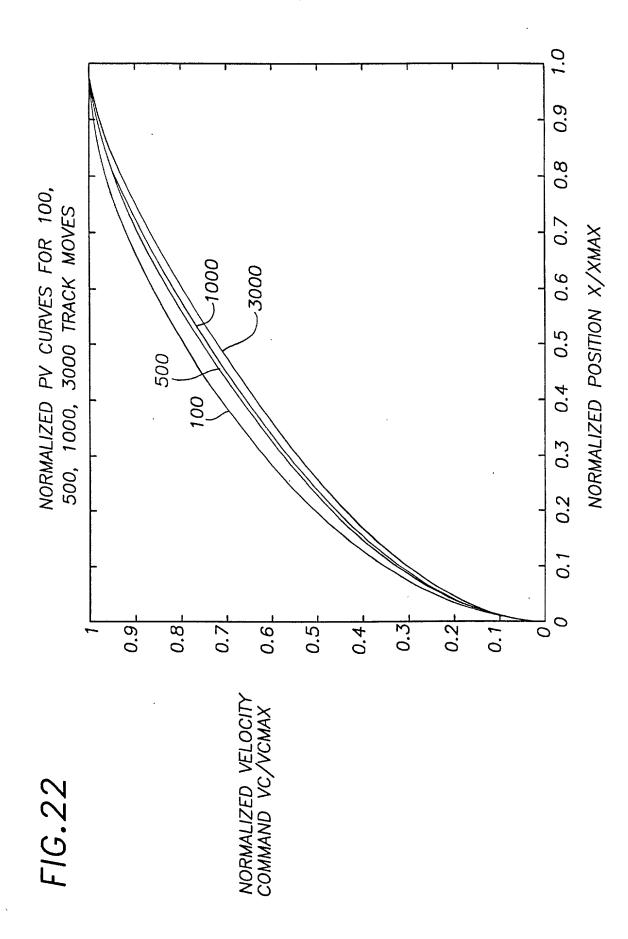




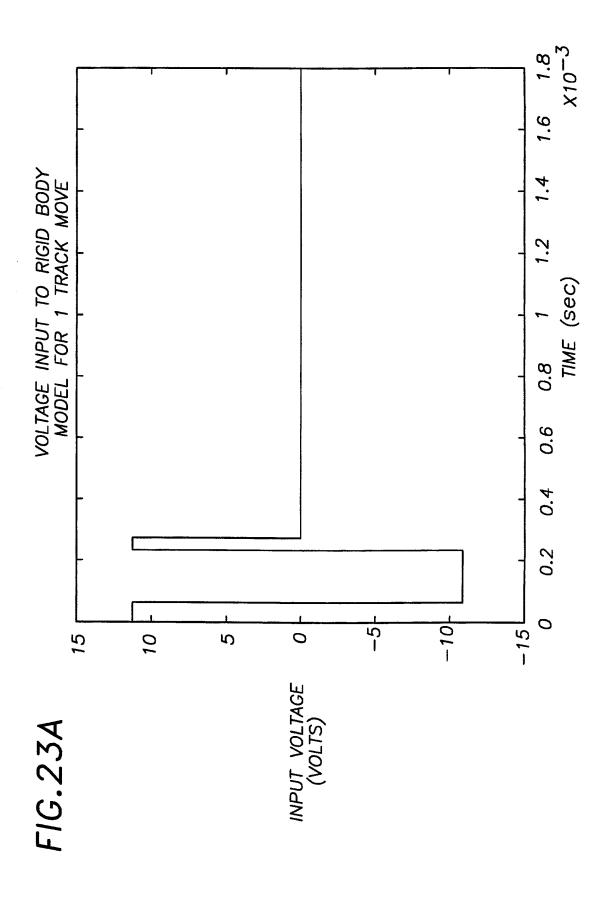


VELOCITY COMMAND (TRACKS/SEC)

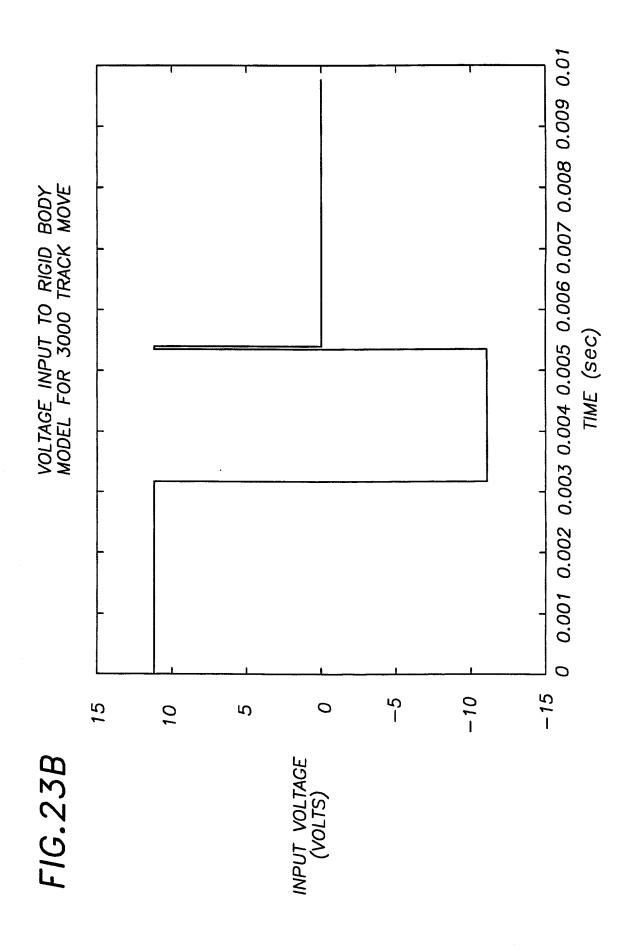




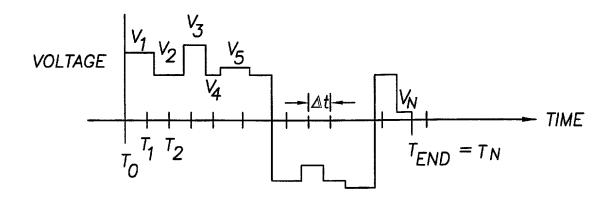








## FIG.24



## FIG.25

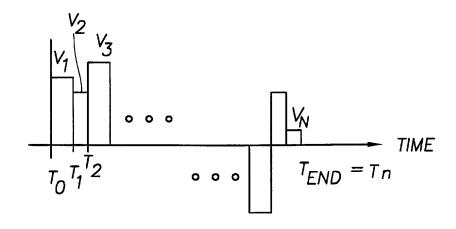
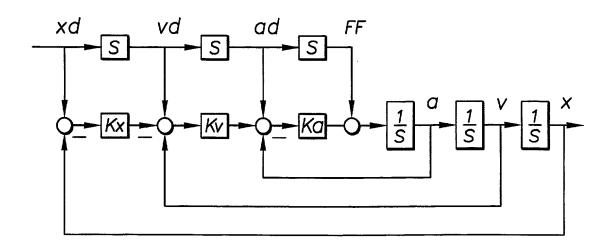
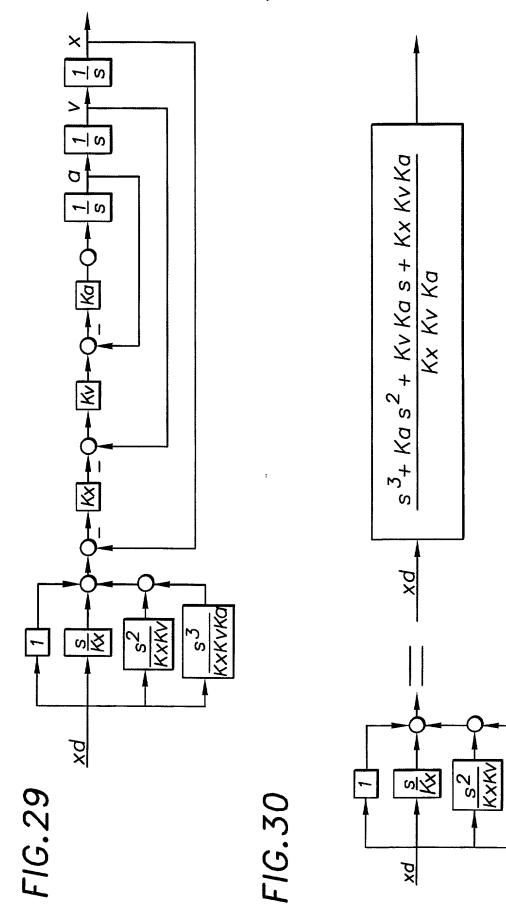


FIG.26

$$\begin{array}{c|c} V_1 & V_2 & V_N \\ \hline \hline T_1 & T_2 & + \circ \circ \circ + & \hline T_{END} \\ \hline T_0 & -V_1 & -V_2 & -V_N \\ \hline \end{array}$$

FIG.28





s3 KXKVKa FIG.31

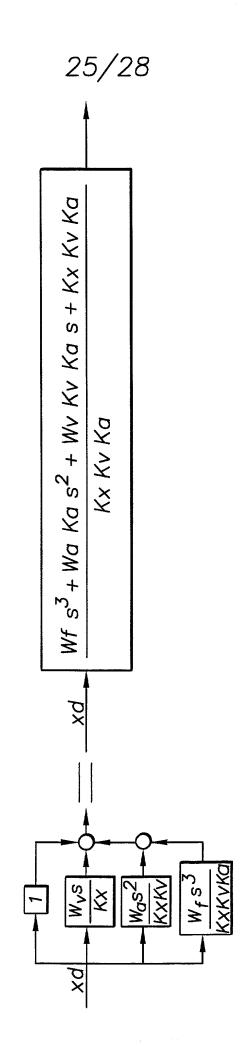
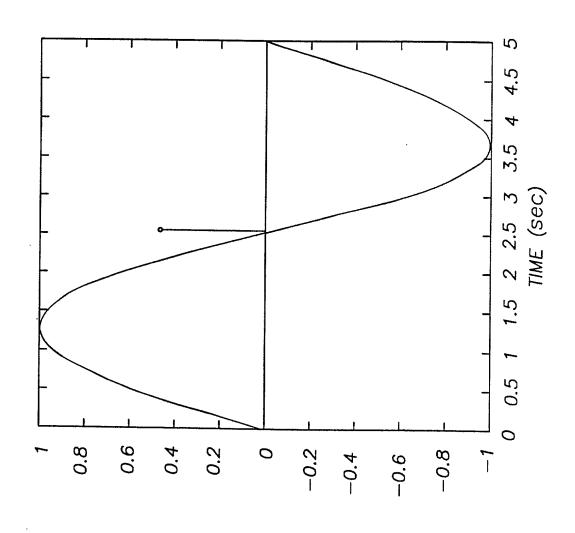


FIG.32



**AMPLITUDE** 

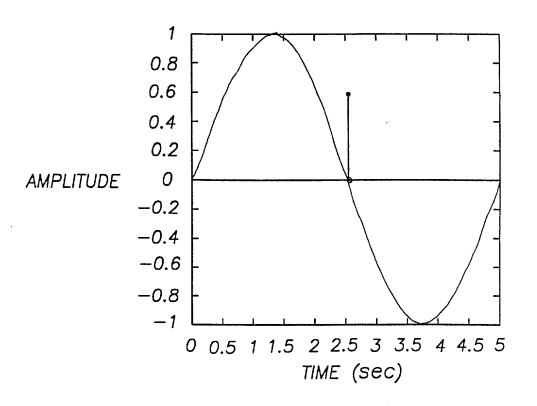


FIG.34

